

27. VECTOR FIELDS IN SPACE

A vector field in space is given by

$$\vec{F} = P\hat{i} + Q\hat{j} + R\hat{k} = \langle P, Q, R \rangle.$$

Here the components, P , Q and R are scalar functions of x , y and z .
 \vec{F} could be a force field;

$$\vec{F} = -\frac{c\langle x, y, z \rangle}{\rho^3},$$

is the force due to gravity. There is both an electric \vec{E} and a magnetic field \vec{B} . There are velocity fields \vec{v} and gradient vector fields.

In space, we can measure the flux of \vec{F} across a **surface** S ,

$$\iint_S \vec{F} \cdot \hat{n} \, dS.$$

Here \hat{n} is a unit normal to the surface. There are two choices of \hat{n} ; we have to choose an orientation, a direction which we decide is positive.

Notation:

$$d\vec{S} = \hat{n} \, dS.$$

Suppose that \vec{F} represents the velocity vector field of some fluid. The amount of water that crosses a small piece of surface in unit time is approximately a parallelepiped with area of base ΔS and height $\vec{F} \cdot \hat{n}$,

$$\vec{F} \cdot \hat{n} \Delta S.$$

Suppose

$$\vec{F} = x\hat{i} + y\hat{j} + z\hat{k},$$

and S is the surface of a sphere of radius a , centred at the origin. Orient the surface S so that the unit normal points outwards,

$$\hat{n} = \frac{1}{a}\langle x, y, z \rangle.$$

In this case

$$\vec{F} \cdot \hat{n} = \frac{1}{a}(x^2 + y^2 + z^2) = a.$$

Hence

$$\iint_S \vec{F} \cdot \hat{n} \, dS = \iint_S a \, dS = 4\pi a^3.$$

Now suppose we work with $\vec{F} = z\hat{k}$. Then

$$\vec{F} \cdot \hat{n} = \frac{z^2}{a}.$$

So the flux is

$$\iint_S \vec{F} \cdot \hat{n} \, dS = \iint_S \frac{z^2}{a} \, dS = \int_0^{2\pi} \int_0^\pi \frac{a^2 \cos^2 \phi}{a} a^2 \sin \phi \, d\phi \, d\theta.$$

The inner integral is

$$\int_0^\pi a^3 \cos^2 \phi \sin \phi \, d\phi \, d\theta = \left[-\frac{a^3}{3} \cos^3 \phi \right]_0^\pi = \frac{2a^3}{3}.$$

The outer integral is

$$\int_0^{2\pi} \frac{2a^3}{3} \, d\theta = \frac{4\pi a^3}{3}.$$

In general, it can be quite hard to parametrise a surface. We will need two parameters to describe the surface and we must express

$$\vec{F} \cdot \hat{n} \, dS,$$

in terms of them. We must also orient the surface:

Question 27.1. *Can one always orient a surface?*

In fact, somewhat surprisingly, the answer is no. The Möbius band is a surface that cannot be oriented.

To begin with, here are some easy special cases:

- (1) If $z = a$ is a horizontal plane then

$$d\vec{S} = \hat{k} \, dx \, dy,$$

(here we choose the upwards orientation).

- (2) For the surface of a sphere of radius a centred at the origin then

$$d\vec{S} = \hat{n} a^2 \sin \phi \, d\phi \, d\theta,$$

where

$$\hat{n} = \frac{1}{a} \langle x, y, z \rangle,$$

so that

$$d\vec{S} = a \sin \phi \langle x, y, z \rangle \, d\phi \, d\theta.$$

- (3) For a cylinder of radius a centred on the z -axis, use z, θ .

$$\hat{n} = \frac{1}{a} \langle x, y, 0 \rangle,$$

which points radially out of the cylinder.

$$dS = a \, dz \, d\theta,$$

so that

$$d\vec{S} = \langle x, y, 0 \rangle \, dz \, d\theta.$$

(4) For the graph of a function $f(x, y)$,

$$d\vec{S} = \langle -f_x, -f_y, 1 \rangle dx dy.$$